



Introducing the Pedestrian Accessibility Tool (PAT)

Open source GIS-based walkability analysis

Conference Paper

Author(s):

Erath, Alexander; van Eggermond, Michael A.B.; [Ordonez Medina, Sergio Arturo](#) ; [Axhausen, Kay W.](#) 

Publication date:

2017-01

Permanent link:

<https://doi.org/10.3929/ethz-b-000207177>

Rights / license:

[In Copyright - Non-Commercial Use Permitted](#)

Von: [Bjelonic Marko](#)
An: [ETH Research Collection](#)
Betreff: Re: AW: Research Collection: A new Journal Article with file was submitted.
Datum: 11. Juni 2020 07:57:03

Thanks for the kind notice.

I would like to clarify the accepted version option. I uploaded the final version that was not edited by the Journal committee. The Journal does some final changes. As far as I know, the Journal of Field Robotics is fine with uploading the final submitted version before the formatting by the Journal. I might have made a mistake and in this case I should change the version of the upload.

Thanks!

Marko

On 11.06.20 07:20, ETH Research Collection wrote:

Dear Mr Bjelonic,

Thank you for the *accepted version* of your journal article in <https://www.research-collection.ethz.ch/handle/20.500.11850/419575>.

Please note that the journal issue cannot yet be accessed as the publisher's DOI <https://doi.org/10.1002/rob.21974> does not resolve. Furthermore, the publisher requires a 12 months' embargo period for *accepted versions*, please refer also to <http://sherpa.ac.uk/romeo/issn/1556-4959/>.

Should you need any further information, please do contact our team.

Yours sincerely,
Research Collection

Françoise Knüsel

—
ETH Zurich, ETH Library, E-Publishing | Research Collection, Rämistrasse 101, 8092 Zurich,
phone +41 44 632 72 22, research-collection@library.ethz.ch, www.research-collection.ethz.ch

Coffee Lectures: Discover our new [bite-sized courses](#), at 15.15 on Wednesday afternoons!

-----Ursprüngliche Nachricht-----

Von: research-collection@library.ethz.ch <research-collection@library.ethz.ch>

Gesendet: 10. Juni 2020 16:40

An: ETH Research Collection <research-collection@library.ethz.ch>

Betreff: Research Collection: A new Journal Article with file was submitted.

A new Item was submitted into the repository:

Title: Perceptive Whole Body Planning for Multi-legged Robots in Confined Spaces

Author(s): Buchanan, Russell; Wellhausen, Lorenz; Bjelonic, Marko;
Bandyopadhyay, Tirthankar; Kottege, Navinda; Hutter, Marco
Submitter: Bjelonic, Marko (marko.bjelonic@mavt.ethz.ch)
URL: <https://www.research-collection.ethz.ch/handle/20.500.11850/419575>

--

Marko Bjelonic
ETH Zürich
+41446322145
www.markobjelonic.com