

## Automatic manifold identification for mNARX models

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# Automatic manifold identification for mNARX models

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## **1 Problem Statement**

**The challenge**: build a surrogate  $\widetilde{\mathcal{M}}$  that emulates the response of a complex time-dependent system  $\mathcal{M}$  over long time periods:

 $y(t) = \mathcal{M}(\boldsymbol{x}(\mathcal{T} \leq t)) \approx \widetilde{\mathcal{M}}(\boldsymbol{x}(\mathcal{T} \leq t))$ 

- Discretized time axis  $\mathcal{T} = \{0, \delta t, 2\delta t, \dots, (N-1)\delta t\}$
- System response  $y: \mathcal{T} \to \mathbb{R}$
- High-dimensional exogenous excitation  $oldsymbol{x}:\mathcal{T}
  ightarrow\mathbb{R}^M$

## 4 Case study

Complex onshore wind turbine simulator with control systems • High-dimensional turbulent wind input:  $v : T \to \mathbb{R}^{3 \times \nu_y \times \nu_z}$ 

• Quantity of interest: Power output  $P: \mathcal{T} \to \mathbb{R}$ 



**Our approach**: Automated incremental construction of an exogenous input manifold suitable for autoregressive surrogates

## **2** Autoregressive Modelling

Nonlinear AutoRegressive with eXogenous input (NARX) models account for both the temporal coherence of the output and exogenous input:

$$y(t) = \widetilde{\mathcal{M}}(\boldsymbol{\varphi}(t), \mathbf{c})$$

Where:

ullet c is a finite set of model parameters/coefficients

•  $\varphi(t)$  collects current and past exogenous inputs and past outputs:  $\begin{aligned} \varphi(t) &= \{y(t - \ell_1^y), y(t - \ell_2^y), \dots, y(t - \ell_{n_y}^y), \\ x_1(t - \ell_1^{x_1}), x_1(t - \ell_2^{x_1}), \dots, x_1(t - \ell_{n_{x_1}}^{x_1}), \\ \dots, \\ x_{M_x}(t - \ell_1^{x_{M_x}}), x_{M_x}(t - \ell_2^{x_{M_x}}), \dots, x_{M_x}(t - \ell_{n_{x_{M_x}}}^{x_{M_x}}) \} \end{aligned}$ • Autoregressive lags  $\ell_i^y \in \{\delta t, 2\delta t, \dots, (N - 1)\delta t\}$ • Exogenous input lags  $\ell_i^{x_j} \in \{0, \delta t, 2\delta t, \dots, (N - 1)\delta t\}$ 

## 3 Exogenous input Manifold



Simulator OpenFAST

Fast-to-construct and evaluate polynomial NARX model

$$y(t) = \sum_{\boldsymbol{\alpha} \in \mathcal{A}} c_{\boldsymbol{\alpha}} \mathcal{P}_{\boldsymbol{\alpha}}(\boldsymbol{\varphi}(t)), \qquad \mathcal{P}_{\boldsymbol{\alpha}}(\boldsymbol{\varphi}(t)) = \prod_{i=1}^{M_{\varphi}} \boldsymbol{\varphi}_{i}(t)^{\alpha_{i}}$$

where the output is represented as sum of monomials  ${\cal P}$  weighted by real-valued coefficients  $c_{lpha}$ 

• Compression of longitudinal wind speeds into spectral coefficients  $\xi$ • Identification of important features with Kendall's  $\tau$  measure of association

## **5** Results

• Left: Kendall's  $\tau$  of manually and automatically selected features

• Right: Corresponding relative coefficient magnitude of the NARX R surrogate Bla



#### **Dimensionality reduction**

Compression of high-dimensional exogenous input  $\boldsymbol{x}:\mathcal{T}\to\mathbb{R}^M$  in its non-temporal coordinates:

 $\boldsymbol{\xi} = \mathcal{G}(\boldsymbol{x})$ 

•  $\boldsymbol{\xi} : \mathcal{T} \to \mathbb{R}^m$  such that  $m \ll M$ •  $\mathcal{G}$  preserves the original time scale

#### Manifold construction

- 1. Collection of existing and derived time-dependent features  $\{z_1 \dots z_n, z_i : \mathcal{T} \to \mathbb{R}\}$ , based on prior knowledge about the system
- 2. Feature selection based on a measure of association  $\rho > \theta$ , e.g.  $\theta = 0.05$ :

 $\rho_{\boldsymbol{z}_i} = \mathcal{Z}(\boldsymbol{z}_i, \boldsymbol{y}), \quad \rho_{\boldsymbol{z}_i} \in \mathbb{R}$ 

3. Construction of NARX model onto exogenous input manifold  $\zeta$ :

 $\hat{y}(t) = \widetilde{\mathcal{M}}(\boldsymbol{\zeta}(\mathcal{T} \leq t), \hat{y}(\mathcal{T} < t)), \quad \boldsymbol{\zeta} = \{\boldsymbol{z_i} \mid \rho_{\boldsymbol{z_i}} > \theta, \boldsymbol{\xi_i} \mid \rho_{\boldsymbol{\xi_i}} > \theta\}$ 

4. Incremental construction of auxiliary quantities during prediction phase:



## **Discussion and Outlook**

#### Discussion

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Multistep approach allows accurate emulation of complex dynamical systems
Relevant features can be automatically selected using a measure of association

a. Simulated power output (black) vs. the emulated one (colored)
a. Most accurate and least accurate prediction

- b. Produced energy computed from simulator output (E) and emulated response ( $\hat{E}$ )
- c. Discrepancy in the produced energy  $(\hat{E} E)$



# $\begin{aligned} z_1(t) &= \mathcal{F}_1(\boldsymbol{\xi}(\mathcal{T} \leq t), z_1(\mathcal{T} < t)) \\ z_2(t) &= \mathcal{F}_2(z_1(\mathcal{T} \leq t), \boldsymbol{\xi}(\mathcal{T} \leq t), z_2(\mathcal{T} < t)) \\ &: \\ z_i(t) &= \mathcal{F}_i(z_1(\mathcal{T} \leq t), \dots, z_{i-1}(\mathcal{T} \leq t), \\ &\quad \boldsymbol{\xi}(\mathcal{T} \leq t), z_i(\mathcal{T} < t)) \end{aligned}$

#### Outlook

• Not only select important features but also determine ideal construction order

• Application to a broader range of problems

#### References

[1] Dimitrov, N., S. Marelli, and S. Schär (2022). Novel surrogate modelling approaches for wind turbine reliability assessment. H2020 Project HIPERWIND. Deliverable D4.1.

## DBAUG



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