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Optimales Rangieren nach Turnieren

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WILLI MAURER

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Prof. Dr. H. Bühlmann, Referent
Prof. Dr. P. Läuchli, Korreferent

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S u m m a r y

The thesis grew out of the attempt to show the optimality (in a decision theoretical sense) of a ranking procedure after knockout tournaments which J. A. Hartigan proposed 1966 in his paper "Probability completion of a knockout tournament" (Ann. Math. Statist. 37, 495 - 503). (He ranks the players according to the mean of the ranking vectors $r = (r_1, r_2, \dots, r_n)$ consistent with the acyclic tournament outcome, where $r_i = k$ means, that player number i has been assigned to the k -th place in the chosen ranking.)

The mathematical model therefore required a more rigorous definition of things like "game", "tournament plan" and "outcome of a tournament" than it has been done so far. Using graph theoretic language, a "tournament plan" \mathcal{P} is interpreted as a mapping of the set \mathcal{T} of all complete digraphs T (with the n players as vertices) into the set \mathcal{D} of all digraphs D of order n , such that a) $\mathcal{P}(T) \subset T$ and b) $\mathcal{P}(T) \subset T^* \implies \mathcal{P}(T^*) = \mathcal{P}(T)$ for all $T, T^* \in \mathcal{T}$. The image $\mathcal{P}(T)$ of \mathcal{P} applied on T is called a "tournament outcome of \mathcal{P} ". A plan $\bar{\mathcal{P}}$ is called "equivalent" to the given plan \mathcal{P} , if there exists a permutation of the players (vertices) which transforms all outcomes $\mathcal{P}(T), T \in \mathcal{T}$, into the outcomes $\bar{\mathcal{P}}(T^*), T^* \in \mathcal{T}$. A plan \mathcal{P} is called "simple" if all possible outcomes of \mathcal{P} are isomorphic; they then are acyclic too. (E. g. symmetric knockout plans on 2^m players are equivalent and simple.) There exist relations between the number of different plans equivalent to a simple plan \mathcal{P} and the number of orders consistent with an outcome of \mathcal{P} .

The model describing the ranking problem is the following: One assumes a) that out of a class K of equivalent plans with only acyclic outcomes a plan \mathcal{P} is chosen at random, b) that the relative "strength" of the players is given by an unknown ranking vector r and finally c) that the outcome $F = \mathcal{P}(T_r)$, where T_r is the transitive complete digraph representing r , can be observed.

The decision problem then is determined by:

$S_n := \{r\}$, space of all ranking vectors r : parameter space,

$\bar{\mathcal{F}} := \{F = \mathcal{P}(T_r); \mathcal{P} \in K, r \in S_n\}$, space of the outcomes: sample space,

$S_n =: \{d\}$: decision space and the loss function $L(d,r)$, $d,r \in S_n$, with $L : S_n \times S_n \rightarrow \mathbb{R}_1^+ \cup \{0\}$.

Given a prior distribution $p := (p_r ; r \in S_n)$ and an outcome F with $R(F)$ the set of all ranking vectors consistent with F , a ranking vector d^* is a Bayes solution iff

$$\sum_{r \in R(F)} L(d^*,r) p_r \leq \sum_{r \in R(F)} L(d,r) p_r \quad \text{for all } d \in S_n .$$

Making two obvious assumptions on L concerning monotony and invariance, one can show that $d^* \in R(F)$. If L furthermore is separable i. e.

$L : (d,r) \mapsto \sum_{i=1}^n f(d_i, r_i)$ then there exist "Branch and Bound" procedures for the search of d^* and finally if the matrix (f) is of a special form, d^* can be found by means of a generalisation of Hartigan's procedure (e. g. if $f(i,j) := v(i)(i - j)$, v monotonically increasing, then d^* is the "Hartigan solution" itself.)

A class of loss functions, different from the separable one, leads to a generalisation and unification of procedures which are already well known in order to rank the players in Round Robin tournaments as e. g. the "row sum"-procedure and Slater's principle of "minimum inconsistencies".

Finally an approach is made to find an optimum "seeding" of the players (i. e. an optimum choice of a plan \mathcal{P} out of a given class K) if prior information on the players' strength is available and a ranking procedure is prescribed.