

Vine copulas for uncertainty quantification: why and how

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[Torre, Emiliano](#) ; [Marelli, Stefano](#) ; Embrechts, Paul; [Sudret, Bruno](#) 

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Vine copulas for Uncertainty Quantification: why and how

Emiliano Torre^{1,2,3}, Stefano Marelli¹,
Paul Embrechts^{2,3}, Bruno Sudret^{1,2}

¹Chair of Risk, Safety and Uncertainty Quantification, ²Risk Center, ³Risk Lab
ETH Zürich, Zürich, Switzerland

8-9 July 2019 – Vine Copulas Workshop, Munich, Germany

Outline

- ① Uncertainty Quantification (UQ)
- ② (Vine) copulas in UQ
- ③ Conclusions

Outline

- 1 Uncertainty Quantification (UQ)
- 2 (Vine) copulas in UQ
- 3 Conclusions

Problem statement

A model \mathcal{M} subject to input \mathbf{X} produces the response Y :

$$Y = \mathcal{M}(\mathbf{X}),$$

where:

- \mathcal{M} : known computational model (black box)
- $\mathbf{X} = (X_1, \dots, X_d)$: real-valued **random vector** with joint cdf $F_{\mathbf{X}}$
- $\Rightarrow Y$ uncertain: real-valued **random variable**

Uncertainty Quantification (UQ): Statistics of Y ?

\mathcal{M} computationally expensive \Rightarrow Monte Carlo **unaffordable** \Rightarrow **faster** methods.

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Uncertainty Quantification (UQ): Statistics of Y ?

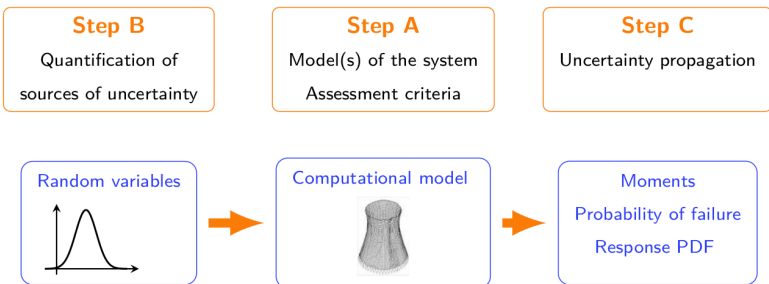
\mathcal{M} computationally expensive \Rightarrow Monte Carlo **unaffordable** \Rightarrow **faster** methods.

UQ analyses and methods

Parameters of $Y = \mathcal{M}(\mathbf{X})$ of interest in UQ:

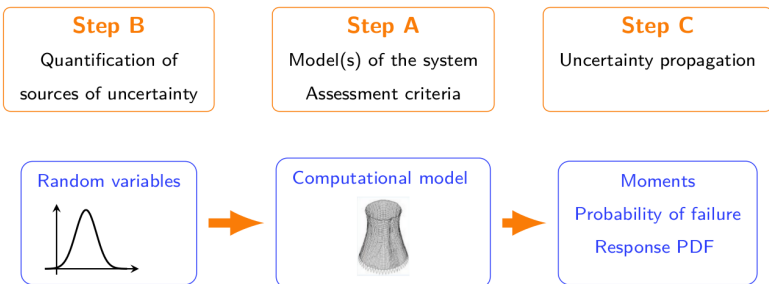
- Global parameters: $\mathbb{E}(Y^k)$, PDF f_Y , ...
↪ Perturbation theory, surrogate modelling
- Tail probabilities, extreme quantiles: $\mathbb{P}(Y \geq y_{\text{critical}})$
↪ Reliability analysis: FORM, SORM, subset simulation, ...
- Conditional tail probabilities: $\mathbb{P}(Y \geq y_{\text{critical}} | X_2 = x_2)$
↪ Fragility analysis
- Sensitivity indices, importance factors
↪ Sensitivity analysis
- ...

Uncertainty analysis: main steps



- Most research in UQ: given \mathcal{M} (step A) and $F_{\mathbf{X}}$ (step B), solve step C. Historically: $\{X_i\}$ assumed independent or with Gaussian copula.
- Focus here: choose a suitable $F_{\mathbf{X}}$ (step B)
 - ↔ Especially a suitable copula. For large d : vines
 - ↔ Map to specific probability spaces needed for some UQ methods

Uncertainty analysis: main steps



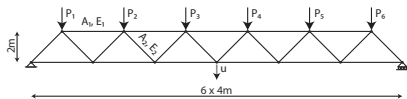
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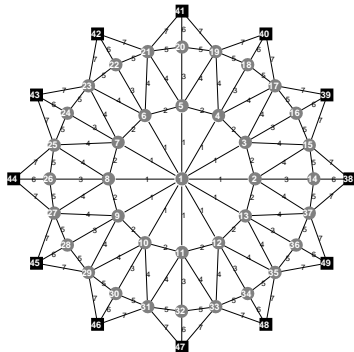
- ① Uncertainty Quantification (UQ)
- ② (Vine) copulas in UQ
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Examples: two finite element models

23 bar horizontal truss (bridge):



120 bar truss (dome):



\mathcal{M} : finite element model

\mathbf{X} : structural parameters
and loads

Y : max deflection Δ

Parameter of Δ of interest:

- $\mathbb{P}(|\Delta| > \delta_{\text{crit}})$

What is coming

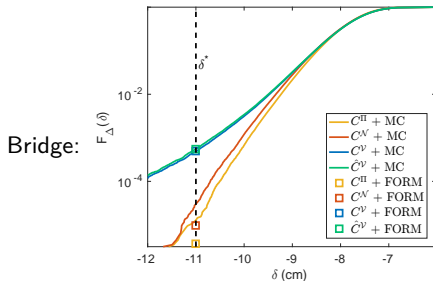
We will:

- Define the **true** joint PDF $f_{\mathbf{X}}$ of X (marginals + vine copula)
- Compute the **reference** solution by large MC simulation, or by FORM

Then, we will forget everything and

- Infer $f_{\mathbf{X}}$ from data (300 multivariate observations)
In particular: Independence, Gaussian, or C-/D-vine copula
↪Q1: does the copula matter?
- Estimate $\mathbb{P}(|\Delta| > \delta_{\text{crit}})$ by large MC simulation and by FORM
for each copula
↪Q2: does the “copula + UQ” framework work?

Reliability analysis by MCS



| Copula Model | Method (# runs) | P_f ($\times 10^{-4}$) |
|-------------------------|-----------------|----------------------------|
| $C^{\mathcal{V}}$ | MC (10^7) | 4.84 |
| $\hat{C}^{\mathcal{V}}$ | MC (10^7) | 5.52 |
| $C^{\mathcal{N}}$ | MC (10^7) | 0.31 |
| C^{Π} | MC (10^7) | 0.13 |

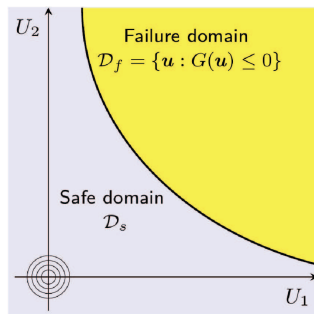
- The copula matters!

First Order Reliability Method (FORM)

Problem: system fails in unknown failure domain \mathcal{D}_f . Failure probability P_f ?

- Assume \mathcal{D}_f convex $\Rightarrow \exists!$ point $U^* \in \mathcal{D}_f$ closest to $\mathbf{0}$
- Assume $F_{\mathbf{X}} = \Phi_d$, d -variate standard normal distribution

Then $P_f \approx 1 - F_{\mathbf{X}}(\mathbf{U}^*) = \Phi_d(-\|\mathbf{U}^*\|)$.

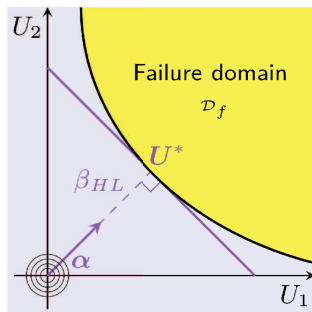


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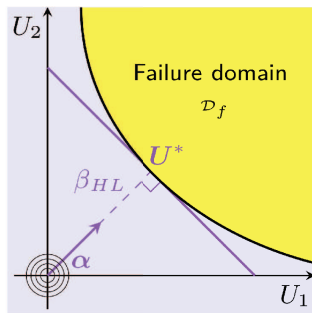
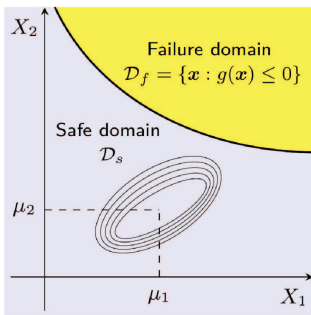


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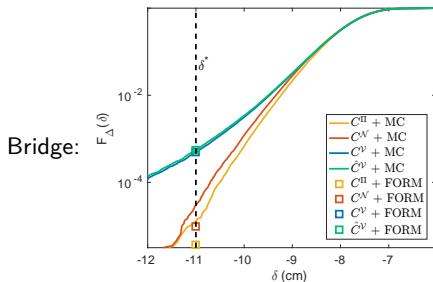
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- Assume $F_X = \Phi_d$, d -variate standard normal distribution

Then $P_f \approx 1 - F_X(U^*) = \Phi_d(-\|U^*\|)$. Task: find U^* .



- If $f_X \neq \Phi_d$: First map $X \mapsto X' \sim \Phi_d$

Reliability analysis: MC vs FORM results

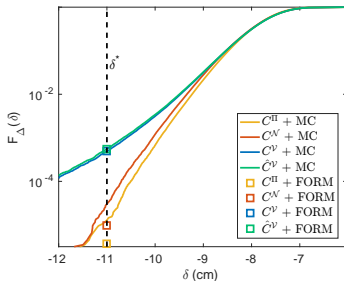


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| $\hat{C}^{\mathcal{N}}$ | MC (10^7) | 0.31 |
| C^{Π} | MC (10^7) | 0.13 |
| $C^{\mathcal{V}}$ | FORM (108) | 4.88 |
| $\hat{C}^{\mathcal{V}}$ | FORM (128) | 5.44 |
| $\hat{C}^{\mathcal{N}}$ | FORM (219) | 0.10 |
| C^{Π} | FORM (219) | 0.04 |

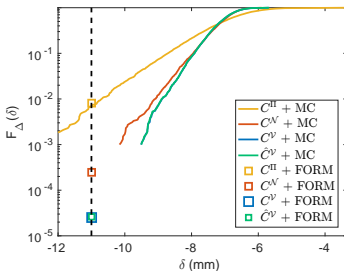
- The copula matters!
- FORM works well in combination with vine copulas

Reliability analysis: MC vs FORM results

Bridge:



Dome:



| Copula Model | Method (# runs) | P_f ($\times 10^{-4}$) |
|--------------|-----------------|----------------------------|
| C^V | MC (10^7) | 4.84 |
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| \hat{C}^N | FORM (219) | 0.10 |
| C^{II} | FORM (219) | 0.04 |

| Copula Model | Method (# runs) | P_f ($\times 10^{-5}$) |
|--------------|-----------------|----------------------------|
| C^V | MC (5000) | — |
| \hat{C}^V | MC (5000) | — |
| \hat{C}^N | MC (5000) | — |
| C^{II} | MC (5000) | 680 |
| C^V | FORM (1988) | 2.53 |
| \hat{C}^V | FORM (3184) | 2.54 |
| \hat{C}^N | FORM (1199) | 25 |
| C^{II} | FORM (1199) | 800 |

Conclusions

- Vine copulas are dependence models suitable to UQ problems:
 - ↔ Enable use of advanced UQ methods when input \mathbf{X} exhibits complex dependencies
 - ↔ Work well in combination with inference
 - ↔ Demonstrated applications in reliability analysis (FORM)
- Code soon available via UQlab:
www.uqlab.com
- For more details:



Probabilistic Engineering Mechanics

Volume 55, January 2019, Pages 1-16



A general framework for data-driven uncertainty quantification under complex input dependencies using vine copulas

Emiliano Torre^{a, b, c, d, e}, Stefano Marelli^b, Paul Embrechts^{c, a, d}, Bruno Sudret^{b, a}

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THANK YOU!



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UQLAB: facts and figures



- \approx 2,000 users
- 930⁺ active users from 77 countries

- Release of V0.9 on July 1st, 2015 (beta version)
- V1.0 on April 28th, 2017
UQLabCore + modules (PCE, Kriging, Sensitivity, Rare events)
- V1.1 on July 1st, 2018
Support vector machines, UQLink
- V1.2 on February 22nd, 2019
Bayesian inversion, UQLib

| Country | # Users |
|----------------|---------|
| United States | 354 |
| China | 224 |
| France | 223 |
| Switzerland | 180 |
| Germany | 134 |
| United Kingdom | 92 |
| Italy | 73 |
| India | 57 |
| Canada | 53 |
| Brazil | 51 |

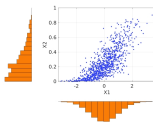
As of May 27, 2019

www.uqlab.com

UQLAB: The Uncertainty Quantification Software

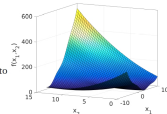
PROBABILISTIC INPUT MODELLING

- Common marginals
- Support for user-defined marginals
- Support for bounds on all distributions (including user-defined)
- Gaussian copula



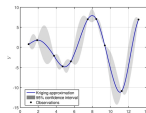
MODELLING FACILITIES

- Simple text strings
- MATLAB m-files
- MATLAB handles
- UQLINK: easily connect UQLAB to third party modelling software



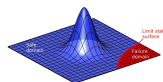
ADVANCED METAMODELLING

- Sparse degree-adaptive Polynomial Chaos Expansions
- Gaussian process modelling (Kriging)
- Polynomial-Chaos Kriging
- Low-rank tensor approximations
- Support vector machines



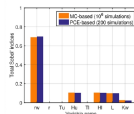
RELIABILITY ANALYSIS (RARE EVENT ESTIMATION)

- FORM/SORM approximation
- Monte Carlo Simulation (MCS)
- Importance Sampling
- Subset Simulation
- Adaptive Kriging (AK-MCS)



SENSITIVITY ANALYSIS

- Correlation-based indices
- Standard Regression Coefficients
- Cotter measure
- Morris indices
- Sampling-based Sobol' indices
- PCE- and LRA-based Sobol' indices
- Borgonovo δ indices
- Support for dependent inputs

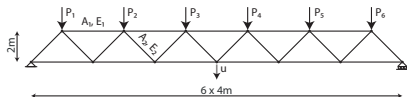


BAYESIAN INVERSION

- Intuitive problem statement
- Advanced MCMC algorithms
- Multi-model support (joint inversion)
- Support for custom likelihood



UQLAB example: Inference of Truss input model



$$\mathbf{X} = (E_1, E_2, A_1, A_2, P_1, \dots, P_6)$$

```

for ii = 1:2      % Assign uncertain Young moduli
    iOpts.Marginals(ii).Type = 'LogNormal';
    iOpts.Marginals(ii).Moments = [2.1e11, 2.1e10];
end
for ii = 3:4     % Assign uncertain cross-sections
    iOpts.Marginals(ii).Inference.Data = A(:,ii-2);
end
for ii = 5:10   % Assign uncertain loads
    iOpts.Marginals(ii).Inference.Data = L(:,ii-4);
end

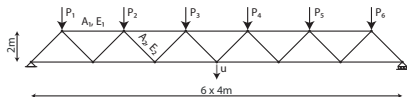
% Define the input copula: product of Independent(dim:4) copula
% and D-Vine copula inferred from data matrix L
iOpts.Copula(1).Type = 'Independent';
iOpts.Copula(1).Parameters = eye(4);

iOpts.Copula(2).Type = 'DVine';
iOpts.Copula(2).Inference.Data = L;

% Create Input
myInput = uq_createInput(iOpts);

```

UQLAB example: Inference of Truss input model



$$\mathbf{X} = (E_1, E_2, A_1, A_2, P_1, \dots, P_6)$$

```
% Create computational model
```

```
mOpts.mHandle = uq_truss_model; % Defined in external m-file
myModel = uq_createModel(mOpts);
```

```
% Create probabilistic input model
```

```
myInput = ... % see previous slide
```

```
% Perform FORM analysis
```

```
aOpts.Type = 'Reliability';
aOpts.Method = 'FORM';
myAnalysis = uq_createAnalysis(aOpts);
```


Polynomial Chaos Expansion (PCE)

PCE model of Y to \mathbf{X} :
$$Y_{PC} = \sum_{\alpha \in \mathbb{N}^d} y_{\alpha} \Psi_{\alpha}(\mathbf{X}),$$

where Ψ_{α} are multivariate polynomials orthonormal wrt $f_{\mathbf{X}}$.

Theorem

If $\mathbb{V}(Y) < \infty$ and $\mathbb{E}(X^k) < \infty \forall k \geq 1$, then $\exists \{y_{\alpha}, \Psi_{\alpha}\} : Y_{PC} \xrightarrow{L^2} Y = \mathcal{M}(X)$.¹

- Properties of coefficients y_{α} : (A) $\mathbb{E}(Y_{PC}) = y_0$, (B) $\mathbb{V}(Y_{PC}) = \sum_{\alpha \neq 0} y_{\alpha}^2$
- (B) guarantees compressibility \Rightarrow parsimonious parametric model
 \hookrightarrow for large d : sparse regression (e.g. least angle regression)
- Provides good estimates of "global" statistics of Y : $\mathbb{E}(Y), \mathbb{V}(Y), f_Y \dots$

How to build the orthonormal basis $\{\Psi_{\alpha}, \alpha \in \mathbb{N}^d\}$?

- If $f_{\mathbf{X}} = \prod_{i=1}^d f_{X_i}$: $\Psi_{\alpha}(\mathbf{x}) := \prod_{i=1}^d \phi_{\alpha_i}^{(i)}(x_i)$, where $\phi_{\alpha_i}^{(i)}$ are univariate polynomials orthonormal wrt f_{X_i} .
- Otherwise: Rosenblatt transform $\mathbf{X} \mapsto \mathbf{X}'$, followed by PCE $Y_{PC}(\mathbf{X}')$

¹Ernst, Mugler, Starkloff, Ullmann (2012), ESAIM:M2AN, 46(2):317-339

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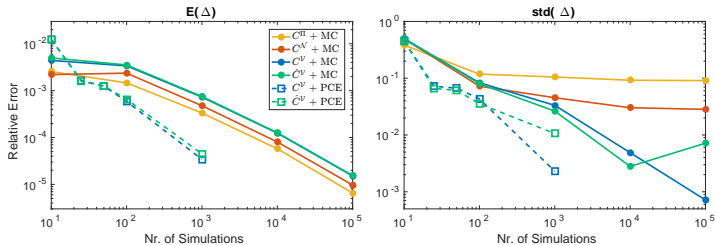
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Vine representations + PCE: errors on $\mathbb{E}(\Delta)$ and $\text{std}(\Delta)$

Bridge (uncertain inputs: 4 structural parameters + 6 loads)



Dome (uncertain inputs: 7 structural parameters + 9 loads)

